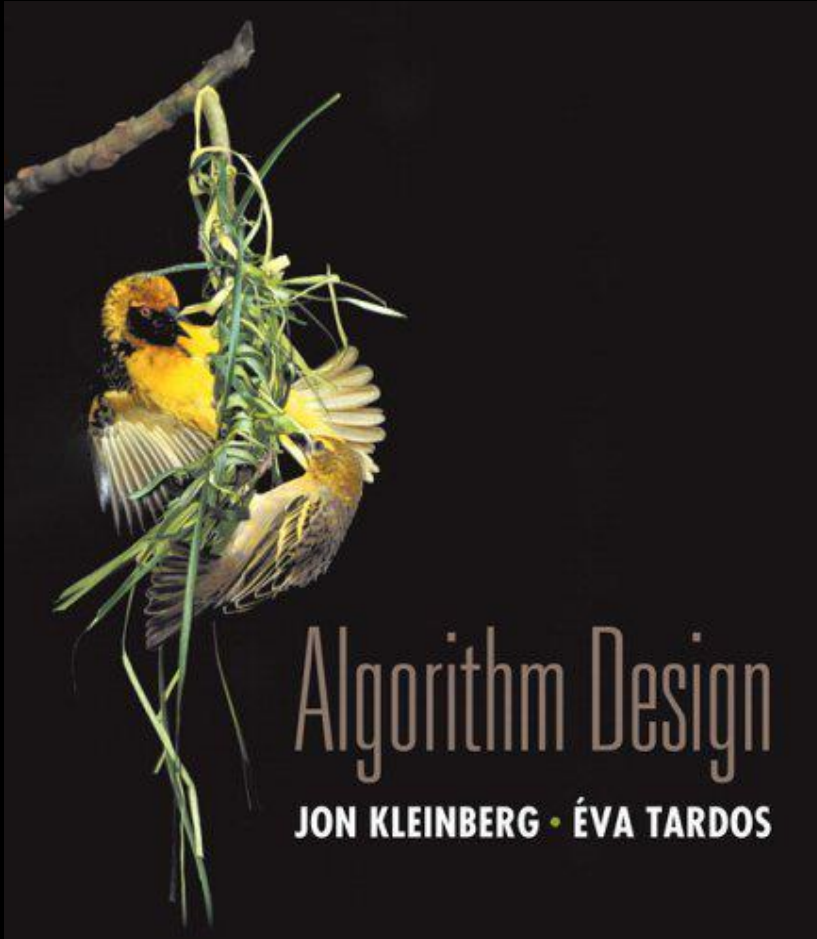


# Chapter 11

## Approximation Algorithms



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# Approximation Algorithms

Q. Suppose I need to solve an NP-hard problem. What should I do?

A. Theory says you're unlikely to find a poly-time algorithm.

Must sacrifice one of three desired features.

- Solve problem to optimality.
- Solve problem in poly-time.
- Solve arbitrary instances of the problem.

$\rho$ -approximation algorithm.

- Guaranteed to run in poly-time.
- Guaranteed to solve arbitrary instance of the problem
- Guaranteed to find solution within ratio  $\rho$  of true optimum.

**Challenge.** Need to prove a solution's value is close to optimum, without even knowing what optimum value is!

# 11.1 Load Balancing

---

# Load Balancing

**Input.**  $m$  identical machines;  $n$  jobs, job  $j$  has processing time  $t_j$ .

- Job  $j$  must run contiguously on one machine.
- A machine can process at most one job at a time.

**Def.** Let  $J(i)$  be the subset of jobs assigned to machine  $i$ . The **load** of machine  $i$  is  $L_i = \sum_{j \in J(i)} t_j$ .

**Def.** The **makespan** is the maximum load on any machine  $L = \max_i L_i$ .


**Load balancing.** Assign each job to a machine to minimize makespan.

# Load Balancing: List Scheduling

## List-scheduling algorithm.

- Consider  $n$  jobs in some fixed order.
- Assign job  $j$  to machine whose load is smallest so far.

*LIST – SCHEDULING*( $m, n, t_1, t_2, \dots, t_n$ )

```
1: for  $i = 1$  to  $m$  do  
2:    $L_i \leftarrow 0$   
3:    $J(i) \leftarrow \emptyset$   
4: end for  
5: for  $j = 1$  to  $n$  do  
6:    $i = \operatorname{argmin}_k L_k$    
7:    $J(i) \leftarrow J(i) \cup j$   
8:    $L_i \leftarrow L_i + t_j$   
9: end for  
10: return  $J(1), \dots, J(m)$ .
```

Implementation.  $O(n \log m)$ .

# Load Balancing: List Scheduling Analysis

**Theorem.** [Graham, 1966] Greedy algorithm is a 2-approximation.

- First worst-case analysis of an approximation algorithm.
- Need to compare resulting solution with optimal makespan  $L^*$ .

**Lemma 1.** The optimal makespan  $L^* \geq \max_j t_j$ .

**Pf.** Some machine must process the most time-consuming job. ▪

**Lemma 2.** The optimal makespan  $L^* \geq \frac{1}{m} \sum_j t_j$ .

**Pf.**

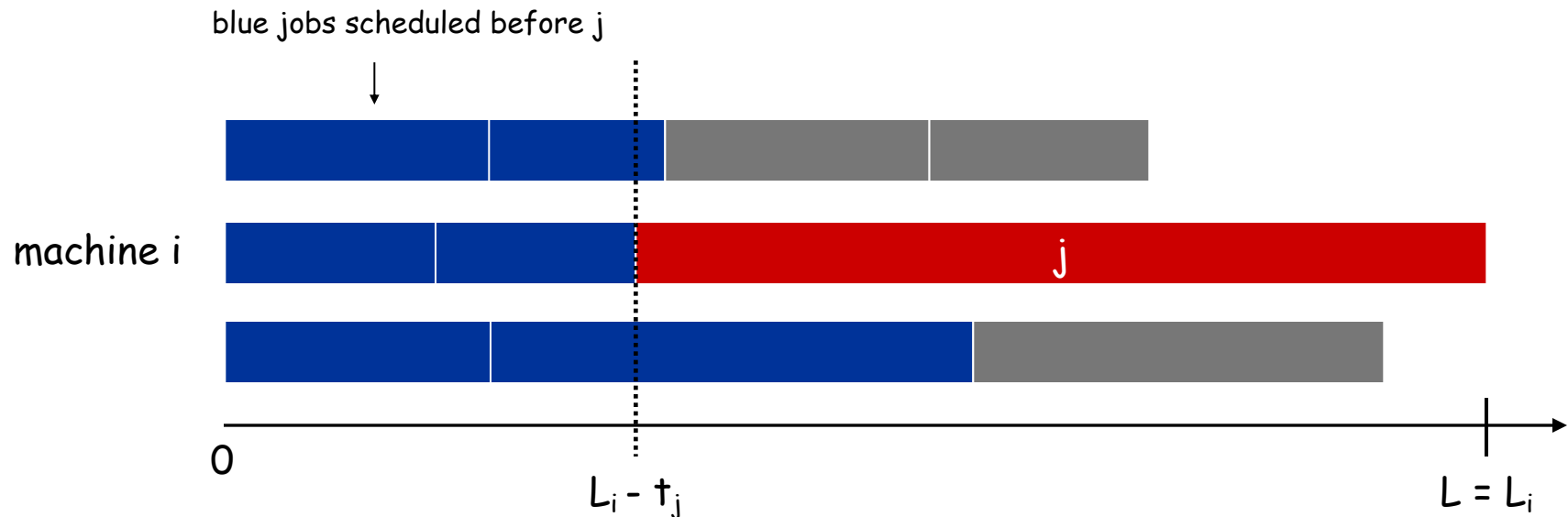
- The total processing time is  $\sum_j t_j$ .
- One of  $m$  machines must do at least a  $1/m$  fraction of total work. ▪

# Load Balancing: List Scheduling Analysis

**Theorem.** Greedy algorithm is a 2-approximation.

**Pf.** Consider load  $L_i$  of bottleneck machine  $i$ .

- Let  $j$  be last job scheduled on machine  $i$ .
- When job  $j$  assigned to machine  $i$ ,  $i$  had smallest load. Its load before assignment is  $L_i - t_j \Rightarrow L_i - t_j \leq L_k$  for all  $1 \leq k \leq m$ .



# Load Balancing: List Scheduling Analysis

**Theorem.** Greedy algorithm is a 2-approximation.

**Pf.** Consider load  $L_i$  of bottleneck machine  $i$ .

- Let  $j$  be last job scheduled on machine  $i$ .
- When job  $j$  assigned to machine  $i$ ,  $i$  had smallest load. Its load before assignment is  $L_i - t_j \Rightarrow L_i - t_j \leq L_k$  for all  $1 \leq k \leq m$ .
- Sum inequalities over all  $k$  and divide by  $m$ :

$$\begin{aligned} L_i - t_j &\leq \frac{1}{m} \sum_k L_k \\ &= \frac{1}{m} \sum_k t_k \\ \text{Lemma 2} \rightarrow &\leq L^* \end{aligned}$$

▪ Now 
$$L_i = \underbrace{(L_i - t_j)}_{\leq L^*} + \underbrace{t_j}_{\leq L^*} \leq 2L^*. \quad \blacksquare$$

↑  
Lemma 1

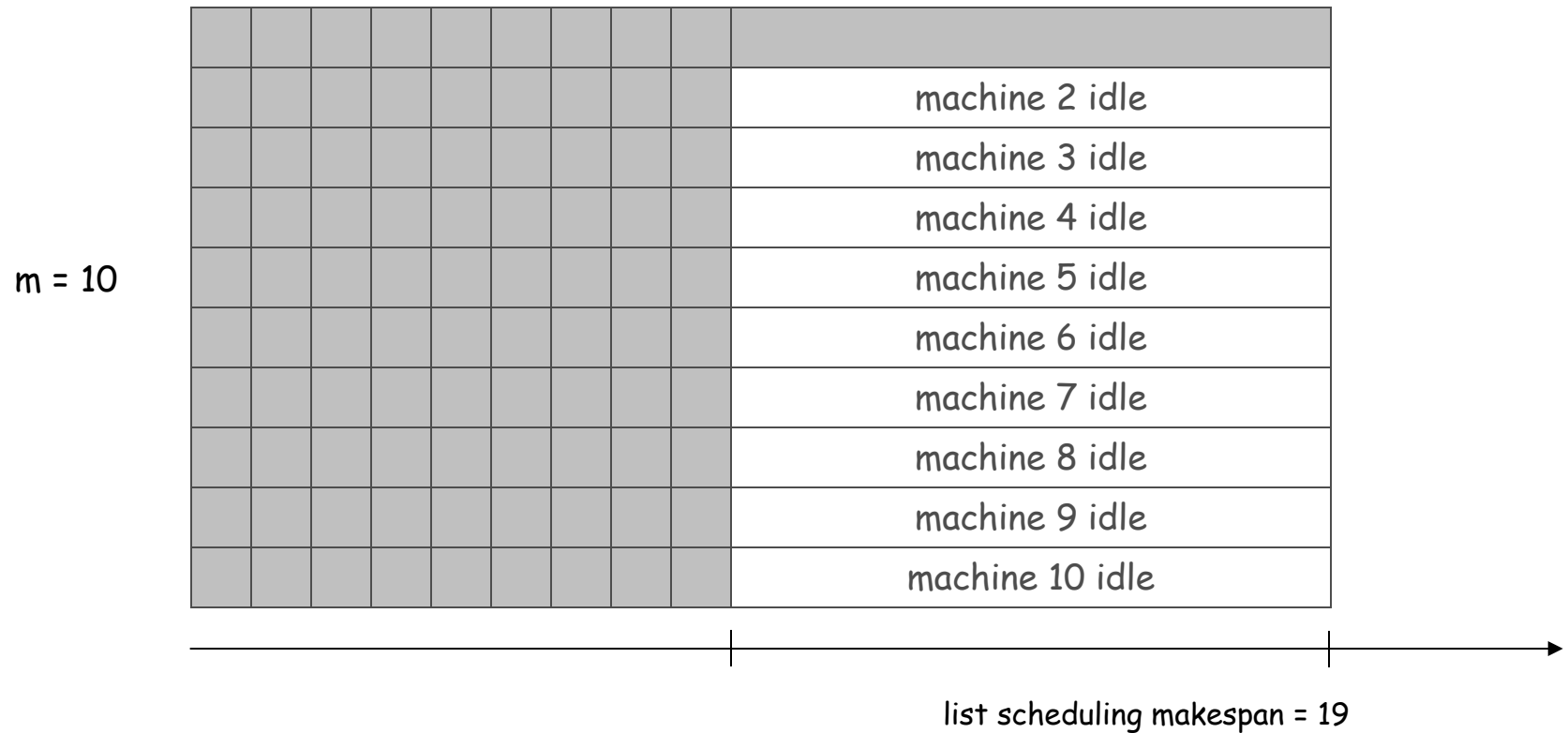


# Load Balancing: List Scheduling Analysis

Q. Is our analysis tight?

A. Essentially yes.

Ex:  $m$  machines,  $m(m-1)$  jobs length 1 jobs, one job of length  $m$

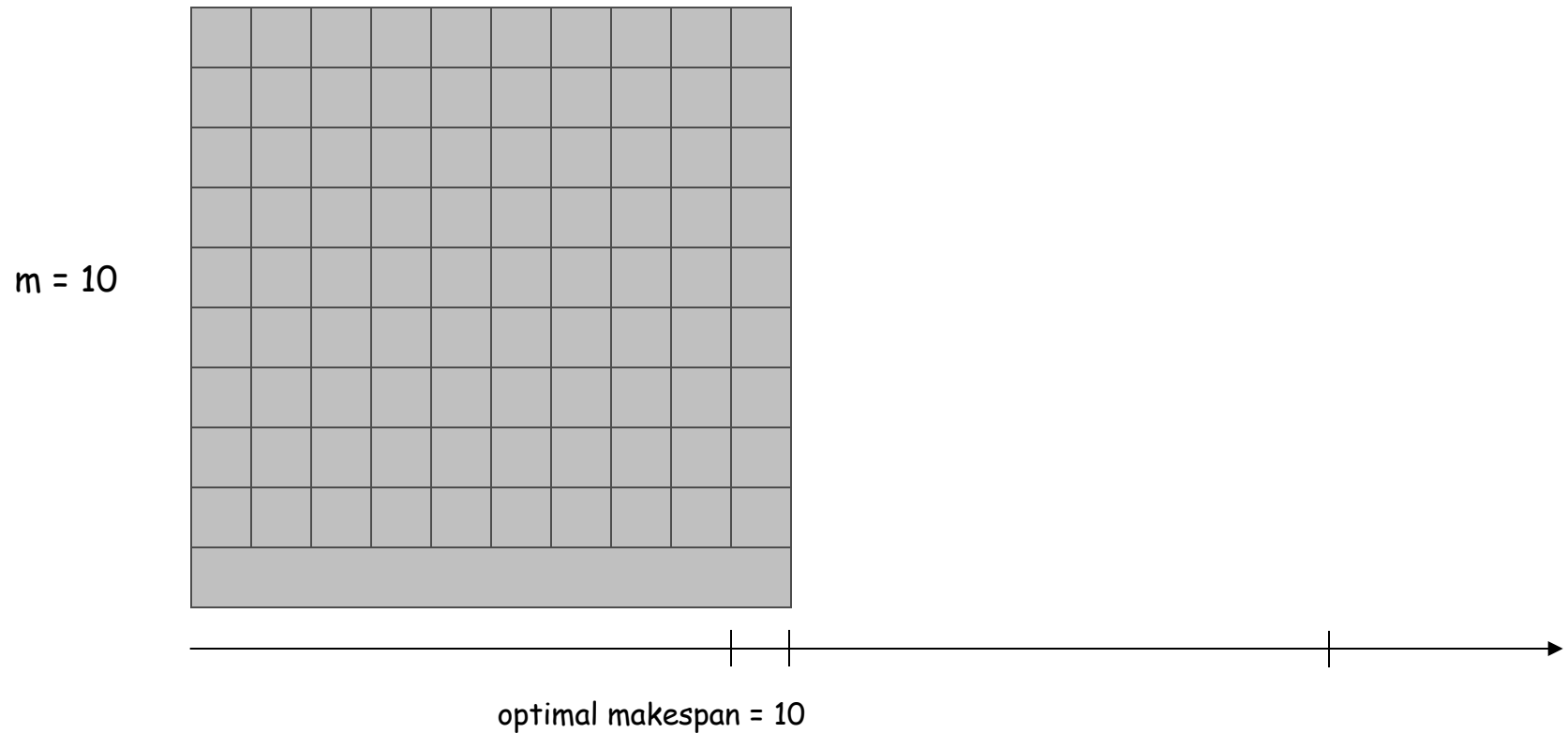


# Load Balancing: List Scheduling Analysis

Q. Is our analysis tight?

A. Essentially yes.

Ex:  $m$  machines,  $m(m-1)$  jobs length 1 jobs, one job of length  $m$



## Load Balancing: LPT Rule

Longest processing time (LPT). Sort  $n$  jobs in descending order of processing time, and then run list scheduling algorithm.

$LPT(m, n, t_1, t_2, \dots, t_n)$

```
1: Sort jobs so that  $t_1 \geq t_2 \geq \dots \geq t_n$ 
2: for  $i = 1$  to  $m$  do
3:    $L_i \leftarrow 0$ 
4:    $J(i) \leftarrow \emptyset$ 
5: end for
6: for  $j = 1$  to  $n$  do
7:    $i = \operatorname{argmin}_k L_k$ 
8:    $J(i) \leftarrow J(i) \cup j$ 
9:    $L_i \leftarrow L_i + t_j$ 
10: end for
11: return  $J(1), \dots, J(m)$ .
```

## Load Balancing: LPT Rule

**Observation.** If at most  $m$  jobs, then list-scheduling is optimal.

**Pf.** Each job put on its own machine. ■

**Lemma 3.** If there are more than  $m$  jobs,  $L^* \geq 2 t_{m+1}$ .

**Pf.**

- Consider first  $m+1$  jobs  $t_1, \dots, t_{m+1}$ .
- Since the  $t_i$ 's are in descending order, each takes at least  $t_{m+1}$  time.
- There are  $m+1$  jobs and  $m$  machines, so by pigeonhole principle, at least one machine gets two jobs. ■

**Theorem.** LPT rule is a  $3/2$  approximation algorithm.

**Pf.** Same basic approach as for list scheduling.

$$L_i = \underbrace{(L_i - t_j)}_{\leq L^*} + \underbrace{t_j}_{\leq \frac{1}{2}L^*} \leq \frac{3}{2}L^*. \quad \blacksquare$$

↑  
Lemma 3  
(by observation, can assume number of jobs  $> m$ )

## Load Balancing: LPT Rule

Q. Is our  $3/2$  analysis tight?

A. No.

Theorem. [Graham, 1969] LPT rule is a  $4/3$ -approximation.

Pf. More sophisticated analysis of same algorithm.

Q. Is Graham's  $4/3$  analysis tight?

A. Essentially yes.

Ex:  $m$  machines,  $n = 2m+1$  jobs, 2 jobs of length  $m+1, m+2, \dots, 2m-1$  and one job of length  $m$ .

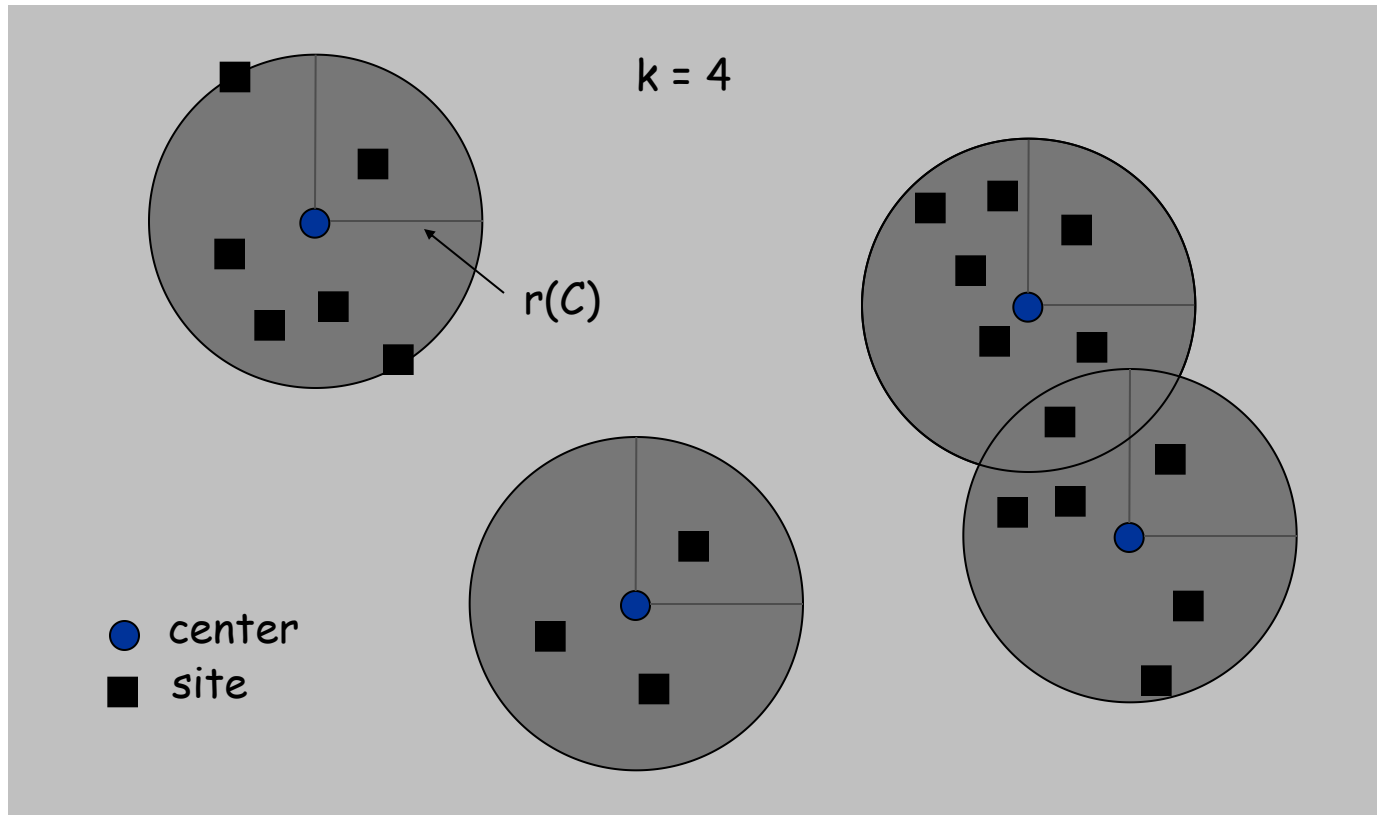
## 11.2 Center Selection

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# Center Selection Problem

**Input.** Set of  $n$  sites  $s_1, \dots, s_n$ .

**Center selection problem.** Select  $k$  centers  $C$  so that maximum distance from a site to nearest center is minimized.



# Center Selection Problem

**Input.** Set of  $n$  sites  $s_1, \dots, s_n$ .

**Center selection problem.** Select  $k$  centers  $C$  so that maximum distance from a site to nearest center is minimized.

**Notation.**

- $\text{dist}(x, y)$  = distance between  $x$  and  $y$ .
- $\text{dist}(s_i, C) = \min_{c \in C} \text{dist}(s_i, c)$  = distance from  $s_i$  to closest center.
- $r(C) = \max_i \text{dist}(s_i, C)$  = smallest covering radius.

**Goal.** Find set of centers  $C$  that minimizes  $r(C)$ , subject to  $|C| = k$ .

**Distance function properties.**

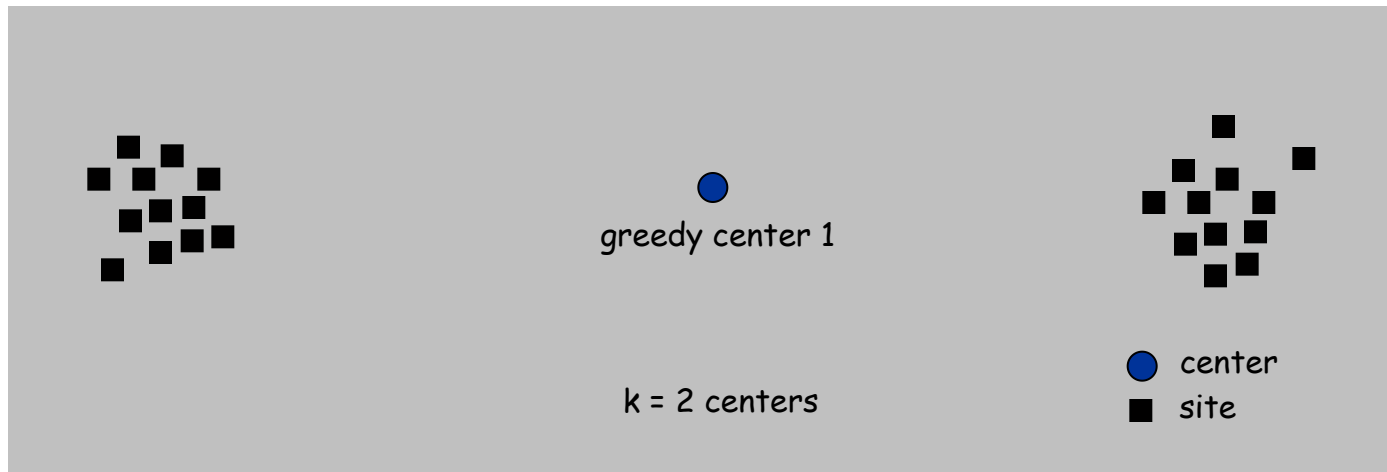
- $\text{dist}(x, x) = 0$  (identity)
- $\text{dist}(x, y) = \text{dist}(y, x)$  (symmetry)
- $\text{dist}(x, y) \leq \text{dist}(x, z) + \text{dist}(z, y)$  (triangle inequality)



# Greedy Algorithm: A False Start

**Greedy algorithm.** Put the first center at the best possible location for a single center, and then keep adding centers so as to reduce the covering radius each time by as much as possible.

**Remark:** arbitrarily bad!



## Center Selection: Greedy Algorithm

**Greedy algorithm.** Repeatedly choose the next center to be the site **farthest** from any existing center.

**GREEDY – CENTER – SELECTION**( $k, n, s_1, s_2, \dots, s_n$ )

```
1:  $C \leftarrow \emptyset$ .  
2: for  $i = 1$  to  $k$  do  
3:   Select a site  $s_i$  with maximum distance  $dist(s_i, C)$   
4:    $C \leftarrow C \cup s_i$   
5: end for  
6: return  $C$ 
```

**Observation.** Upon termination all centers in  $C$  are pairwise at least  $r(C)$  apart.

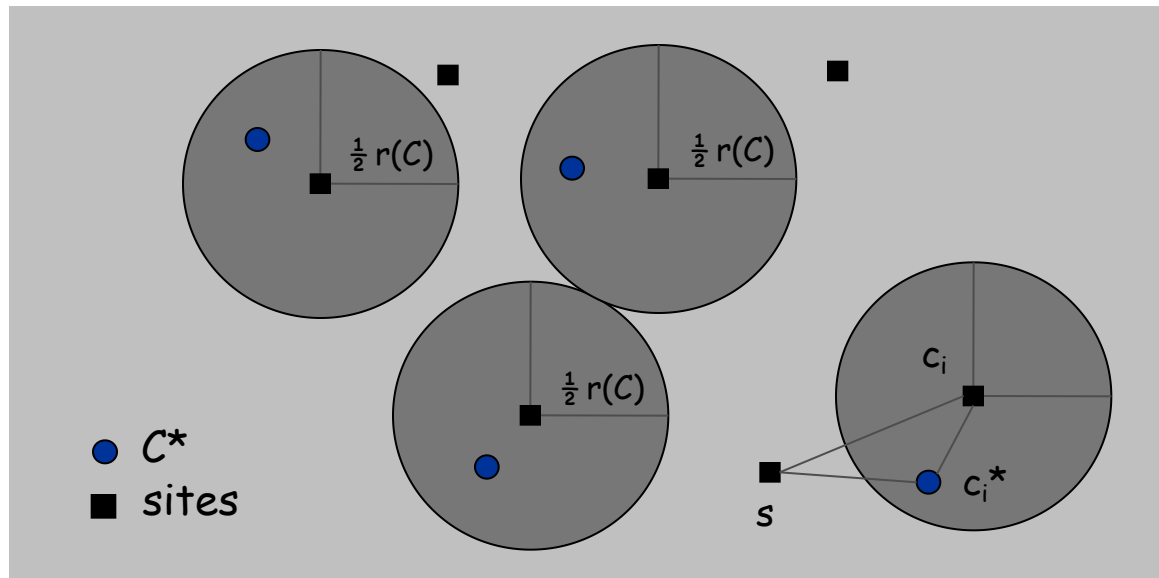
**Pf.** By construction of algorithm.

# Center Selection: Analysis of Greedy Algorithm

**Theorem.** Let  $C^*$  be an optimal set of centers. Then  $r(C) \leq 2r(C^*)$ .

**Pf.** (by contradiction) Assume  $r(C^*) < \frac{1}{2} r(C)$ .

- For each site  $c_i$  in  $C$ , consider ball of radius  $\frac{1}{2} r(C)$  around it.
- Exactly one  $c_i^*$  in each ball; let  $c_i$  be the site paired with  $c_i^*$ .
- Consider any site  $s$  and its closest center  $c_i^*$  in  $C^*$ .
- $\text{dist}(s, C) \leq \text{dist}(s, c_i) \leq \text{dist}(s, c_i^*) + \text{dist}(c_i^*, c_i) \leq 2r(C^*)$ .
- Thus  $r(C) \leq 2r(C^*)$ .
  - $\Delta$ -inequality
  - $\leq r(C^*)$  since  $c_i^*$  is closest center



# Center Selection

**Theorem.** Greedy algorithm is a 2-approximation for center selection problem.

**Question.** Is there hope of a  $3/2$ -approximation?  $4/3$ ?

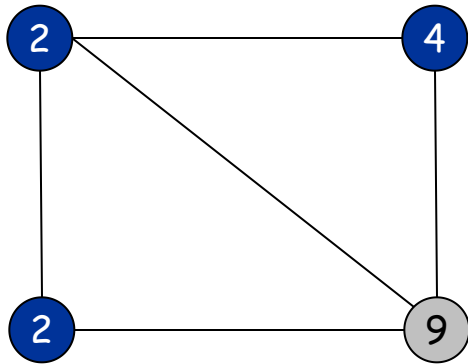
**Theorem.** Unless  $P = NP$ , there no  $\rho$ -approximation for center-selection problem for any  $\rho < 2$ .

## 11.4 The Pricing Method: Vertex Cover

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# Weighted Vertex Cover

**Weighted vertex cover.** Given a graph  $G$  with vertex weights, find a vertex cover of minimum weight.



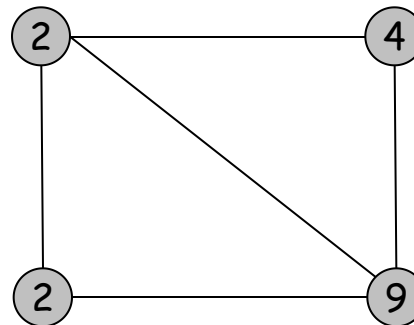
$$\text{weight} = 2 + 2 + 4$$

# Weighted Vertex Cover

**Pricing method.** Each edge must be covered by some vertex  $i$ . Edge  $e$  pays price  $p_e \geq 0$  to use vertex  $i$ .

**Fairness.** Edges incident to vertex  $i$  should pay  $\leq w_i$  in total.

$$\text{for each vertex } i: \sum_{e=(i,j)} p_e \leq w_i$$



**Lemma.** For any vertex cover  $S$  and any fair prices  $p_e$ :  $\sum_e p_e \leq w(S)$ .

**Proof.** ■

$$\sum_{e \in E} p_e \leq \sum_{i \in S} \sum_{e=(i,j)} p_e \leq \sum_{i \in S} w_i = w(S).$$

↑ each edge  $e$  covered by at least one node in  $S$

↑ sum fairness inequalities for each node in  $S$

## Pricing Method

Pricing method. Set prices and find vertex cover simultaneously.

### *WEIGHTED – VERTEX – COVER*( $G, w$ )

```
1:  $S \leftarrow \emptyset$ 
2: for each  $e \in E$  do
3:    $p_i \leftarrow 0$ .
4: end for
5: while there exists an edge  $(i, j)$  such that neither  $i$  nor  $j$  is
   tight) do
6:   Select such an edge  $e = (i, j)$ .
7:   Increase  $p_e$  as much as possible until  $i$  or  $j$  is tight.
8: end while
9:  $S \leftarrow$  set of all tight nodes.
10: return  $S$ .
```



# Pricing Method

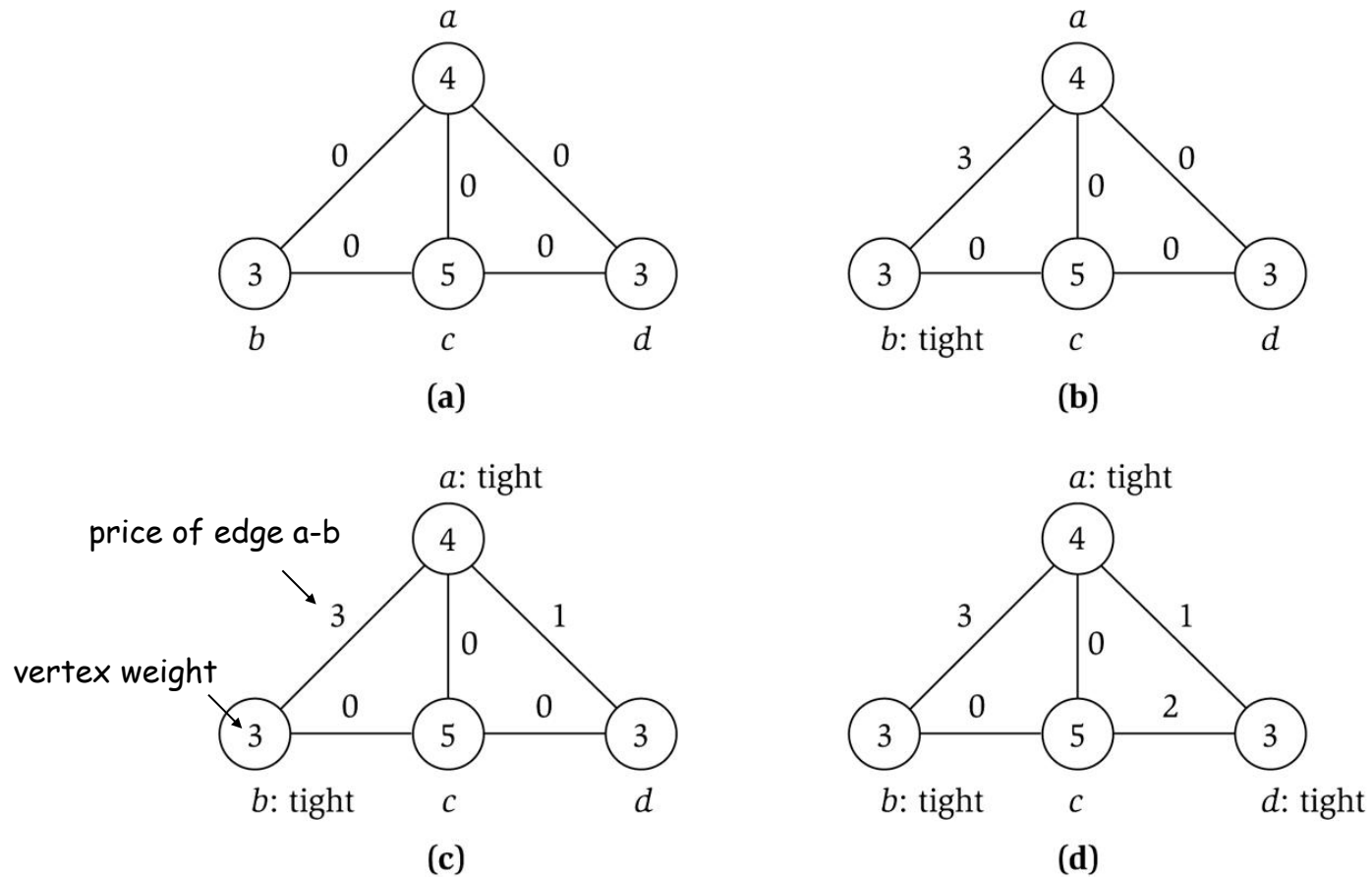


Figure 11.8

## Pricing Method: Analysis

**Theorem.** Pricing method is a 2-approximation.

**Pf.**

- Algorithm terminates since at least one new node becomes tight after each iteration of while loop.
- Let  $S$  = set of all tight nodes upon termination of algorithm.  $S$  is a vertex cover: if some edge  $i$ - $j$  is uncovered, then neither  $i$  nor  $j$  is tight. But then while loop would not terminate.
- Let  $S^*$  be optimal vertex cover. We show  $w(S) \leq 2w(S^*)$ .

$$w(S) = \sum_{i \in S} w_i = \sum_{i \in S} \sum_{e=(i,j)} p_e \leq \sum_{i \in V} \sum_{e=(i,j)} p_e = 2 \sum_{e \in E} p_e \leq 2w(S^*). \quad \blacksquare$$

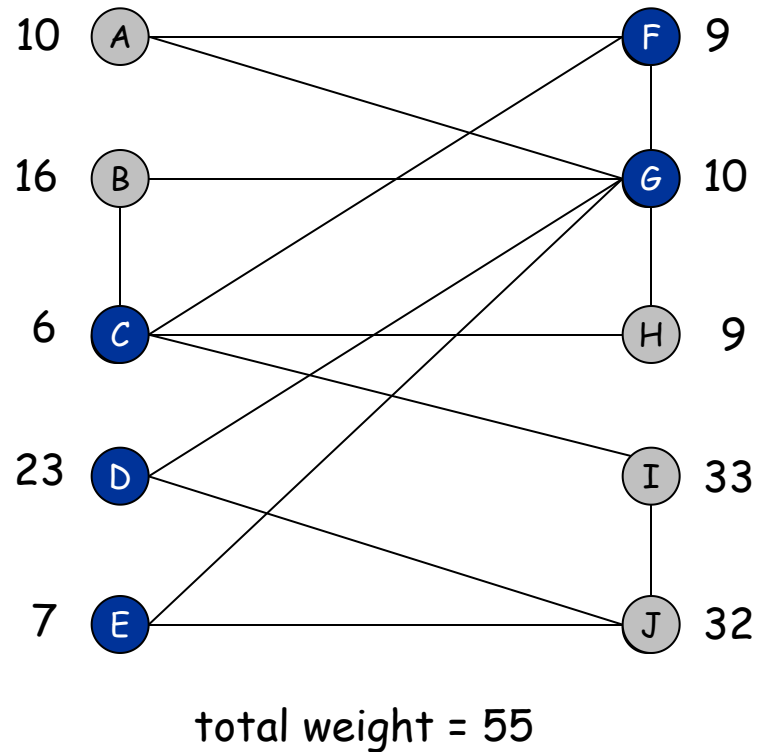
$\uparrow$  all nodes in  $S$  are tight       $\uparrow$   $S \subseteq V$ , prices  $\geq 0$        $\uparrow$  each edge counted twice       $\uparrow$  fairness lemma

## 11.6 LP Rounding: Vertex Cover

---

# Weighted Vertex Cover

**Weighted vertex cover.** Given an undirected graph  $G = (V, E)$  with vertex weights  $w_i \geq 0$ , find a minimum weight subset of nodes  $S$  such that every edge is incident to at least one vertex in  $S$ .



# Weighted Vertex Cover: IP Formulation

**Weighted vertex cover.** Given an undirected graph  $G = (V, E)$  with vertex weights  $w_i \geq 0$ , find a minimum weight subset of nodes  $S$  such that every edge is incident to at least one vertex in  $S$ .

**Integer programming formulation.**

- Model inclusion of each vertex  $i$  using a 0/1 variable  $x_i$ .

$$x_i = \begin{cases} 0 & \text{if vertex } i \text{ is not in vertex cover} \\ 1 & \text{if vertex } i \text{ is in vertex cover} \end{cases}$$

Vertex covers in 1-1 correspondence with 0/1 assignments:

$$S = \{i \in V : x_i = 1\}$$

- Objective function: minimize  $\sum_i w_i x_i$ .
- If  $(i,j) \in E$ , must take either  $i$  or  $j$ :  $x_i + x_j \geq 1$ .

# Weighted Vertex Cover: IP Formulation

Weighted vertex cover. Integer programming formulation.

$$\begin{aligned} (ILP) \quad & \min \quad \sum_{i \in V} w_i x_i \\ & \text{s. t.} \quad x_i + x_j \geq 1 \quad (i, j) \in E \\ & \quad \quad x_i \in \{0, 1\} \quad i \in V \end{aligned}$$

**Observation.** If  $x^*$  is optimal solution to (ILP), then  $S = \{i \in V : x^*_i = 1\}$  is a min weight vertex cover.

# Linear Programming

**Linear programming.** Max/min linear objective function subject to linear inequalities.

- Input: integers  $c_j, b_i, a_{ij}$ .
- Output: **real numbers**  $x_j$ .

$$\begin{aligned} \text{(P)} \quad & \max \quad \sum_{j=1}^n c_j x_j \\ & \text{s. t.} \quad \sum_{j=1}^n a_{ij} x_j \geq b_i \quad 1 \leq i \leq m \\ & \quad \quad \quad x_j \geq 0 \quad 1 \leq j \leq n \end{aligned}$$

**Simplex algorithm.** [Dantzig 1947] Can solve LP in practice.

**Ellipsoid algorithm.** [Khachian 1979] Can solve LP in poly-time.

**Interior Point Method.** [Karmarkar 1984] Can solve LP in poly-time and in practice.

# Weighted Vertex Cover: LP Relaxation

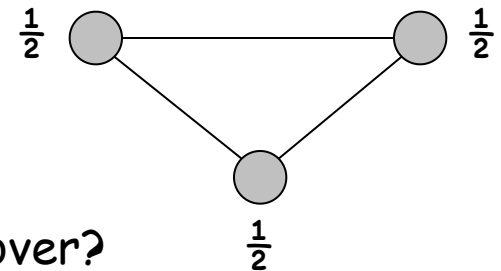
Weighted vertex cover. Linear programming formulation.

$$\begin{aligned} (LP) \quad & \min \quad \sum_{i \in V} w_i x_i \\ & \text{s. t.} \quad x_i + x_j \geq 1 \quad (i, j) \in E \\ & \quad \quad x_i \geq 0 \quad i \in V \end{aligned}$$

Observation. Optimal value of (LP) is  $\leq$  optimal value of (ILP).

Pf. LP has fewer constraints.

Note. LP is not equivalent to vertex cover.



Q. How can solving LP help us find a small vertex cover?

A. Solve LP and **round** fractional values.



## Weighted Vertex Cover

**Theorem.** If  $x^*$  is optimal solution to (LP), then  $S = \{i \in V : x^*_i \geq \frac{1}{2}\}$  is a vertex cover whose weight is at most twice the min possible weight.

**Pf.** [ $S$  is a vertex cover]

- Consider an edge  $(i, j) \in E$ .
- Since  $x^*_i + x^*_j \geq 1$ , either  $x^*_i \geq \frac{1}{2}$  or  $x^*_j \geq \frac{1}{2} \Rightarrow (i, j)$  covered.

**Pf.** [ $S$  has desired cost]

- Let  $S^*$  be optimal vertex cover. Then

$$\sum_{i \in S^*} w_i \geq \sum_{i \in V} w_i x_i^* \geq \sum_{i \in S} w_i x_i^* \geq \frac{1}{2} \sum_{i \in S} w_i.$$


↑  
LP is a relaxation

↑  
 $x^*_i \geq \frac{1}{2}$

# Weighted Vertex Cover

**Theorem.** 2-approximation algorithm for weighted vertex cover.

**Theorem.** [Dinur-Safra 2001] If  $P \neq NP$ , then no  $\rho$ -approximation for  $\rho < 1.3607$ , even with unit weights.


$$10\sqrt{5} - 21$$

**Open research problem.** Close the gap.

# 11.8 Knapsack Problem

---

# Polynomial Time Approximation Scheme

**PTAS.**  $(1 + \varepsilon)$ -approximation algorithm for any constant  $\varepsilon > 0$ .

**Consequence.** PTAS produces arbitrarily high quality solution, but trades off accuracy for time.

**This section.** PTAS for knapsack problem via rounding and scaling.

# Knapsack Problem

## Knapsack problem.

- Given  $n$  objects and a "knapsack."
- Item  $i$  has value  $v_i > 0$  and weighs  $w_i > 0$ . ← we'll assume  $w_i \leq W$
- Knapsack can carry weight up to  $W$ .
- Goal: fill knapsack so as to maximize total value.

Ex: { 3, 4 } has value 40.

$$W = 11$$

| Item | Value | Weight |
|------|-------|--------|
| 1    | 1     | 1      |
| 2    | 6     | 2      |
| 3    | 18    | 5      |
| 4    | 22    | 6      |
| 5    | 28    | 7      |

# Knapsack is NP-Complete

**KNAPSACK:** Given a finite set  $X$ , positive weights  $w_i$ , positive values  $v_i$ , a weight limit  $W$ , and a target value  $V$ , is there a subset  $S \subseteq X$  such that:

$$\begin{aligned}\sum_{i \in S} w_i &\leq W \\ \sum_{i \in S} v_i &\geq V\end{aligned}$$

**SUBSET-SUM:** Given a finite set  $X$ , positive values  $u_i$ , and an integer  $U$ , is there a subset  $S \subseteq X$  whose elements sum to exactly  $U$ ?

**Claim.** SUBSET-SUM  $\leq_p$  KNAPSACK.

**Pf.** Given instance  $(u_1, \dots, u_n, U)$  of SUBSET-SUM, create KNAPSACK instance:

$$\begin{aligned}v_i = w_i = u_i & \quad \sum_{i \in S} u_i \leq U \\ V = W = U & \quad \sum_{i \in S} u_i \geq U\end{aligned}$$

# Knapsack Problem: Dynamic Programming 1

**Def.**  $OPT(i, w)$  = max value subset of items  $1, \dots, i$  with weight limit  $w$ .

- Case 1:  $OPT$  does not select item  $i$ .
  - $OPT$  selects best of  $1, \dots, i-1$  using up to weight limit  $w$
- Case 2:  $OPT$  selects item  $i$ .
  - new weight limit =  $w - w_i$
  - $OPT$  selects best of  $1, \dots, i-1$  using up to weight limit  $w - w_i$

$$OPT(i, w) = \begin{cases} 0 & \text{if } i = 0 \\ OPT(i-1, w) & \text{if } w_i > w \\ \max \{ OPT(i-1, w), v_i + OPT(i-1, w - w_i) \} & \text{otherwise} \end{cases}$$

**Running time.**  $O(n W)$ .

- $W$  = weight limit.
- **Not polynomial** in input size!

# Knapsack Problem: Dynamic Programming II

**Def.**  $OPT(i, v)$  = min weight subset of items 1, ..., i that yields value **exactly** v.

- Case 1: OPT does not select item i.
  - OPT selects best of 1, ..., i-1 that achieves exactly value v
- Case 2: OPT selects item i.
  - consumes weight  $w_i$ , new value needed =  $v - v_i$
  - OPT selects best of 1, ..., i-1 that achieves exactly value v

$$OPT(i, v) = \begin{cases} 0 & \text{if } v = 0 \\ \infty & \text{if } i = 0, v > 0 \\ OPT(i-1, v) & \text{if } v_i > v \\ \min \{ OPT(i-1, v), w_i + OPT(i-1, v - v_i) \} & \text{otherwise} \end{cases}$$

$$V^* \leq n v_{\max}$$

**Running time.**  $O(n V^*) = O(n^2 v_{\max})$ .

- $V^*$  = optimal value = maximum v such that  $OPT(n, v) \leq W$ .
- **Not polynomial** in input size!



# Knapsack: FPTAS

## Intuition for approximation algorithm.

- Round all values up to lie in smaller range.
- Run dynamic programming algorithm on rounded instance.
- Return the best of optimal items in rounded instance and the item with largest value.

| Item | Value      | Weight |
|------|------------|--------|
| 1    | 134,221    | 1      |
| 2    | 656,342    | 2      |
| 3    | 1,810,013  | 5      |
| 4    | 22,217,800 | 6      |
| 5    | 28,343,199 | 7      |

$W = 11$

original instance



| Item | Value | Weight |
|------|-------|--------|
| 1    | 2     | 1      |
| 2    | 7     | 2      |
| 3    | 19    | 5      |
| 4    | 23    | 6      |
| 5    | 29    | 7      |

$W = 11$

rounded instance

# Knapsack: FPTAS

Knapsack FPTAS. Round up all values:  $\bar{v}_i = \left\lceil \frac{v_i}{\theta} \right\rceil$ ,  $\hat{v}_i = \left\lfloor \frac{v_i}{\theta} \right\rfloor$

- $v_{\max}$  = largest value in original instance
- $\varepsilon$  = precision parameter
- $\theta$  = scaling factor =  $\varepsilon v_{\max} / n$

**Observation.** Optimal solution to problems with  $\bar{v}$  or  $\hat{v}$  are equivalent.

**Intuition.**  $\bar{v}$  close to  $v$  so optimal solution using  $\bar{v}$  is nearly optimal;  
 $\hat{v}$  small and integral so dynamic programming algorithm is fast.

**Running time.**  $O(n^3 / \varepsilon)$ .

- Dynamic program II running time is  $O(n^2 \hat{v}_{\max})$ , where

$$\hat{v}_{\max} = \left\lfloor \frac{v_{\max}}{\theta} \right\rfloor = \left\lfloor \frac{n}{\varepsilon} \right\rfloor$$

# Knapsack: FPTAS

Knapsack FPTAS. Round up all values:  $\bar{v}_i = \left\lceil \frac{v_i}{\theta} \right\rceil \theta$

**Theorem.** If  $S$  is solution found by our algorithm and  $S^*$  is any other feasible solution then  $(1+\varepsilon) \sum_{i \in S} v_i \geq \sum_{i \in S^*} v_i$

**Pf.** Let  $S^*$  be any feasible solution satisfying weight constraint.

$$\sum_{i \in S^*} v_i \leq \sum_{i \in S^*} \bar{v}_i$$

always round up

$$\leq \sum_{i \in S} \bar{v}_i$$

solve rounded instance optimally

$$\leq \sum_{i \in S} (v_i + \theta)$$

never round up by more than  $\theta$

$$\leq \sum_{i \in S} v_i + n\theta$$

$|S| \leq n$

$$\leq (1+\varepsilon) \sum_{i \in S} v_i$$

DP alg can take  $v_{\max}$   
 $\downarrow$   
 $n\theta = \varepsilon v_{\max}, v_{\max} \leq \sum_{i \in S} v_i$